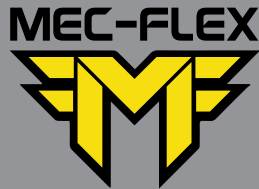


PRODUCT DATA SHEET



ELG0100

MEC-FLEX UTILITY HIGH VISIBILITY MECHANICS SAFETY GLOVES

Mec-Flex Series Glove

MEC-FLEX UTILITY HIGH VISIBILITY MECHANICS SAFETY GLOVES

Mec-Flex® Utility High Vis is a comfortable form fitting glove designed for general day-to-day handling tasks where you need to be seen. The single layer Hyde-Tex 85 palm has silicon fingertips to provide addition grip. The elastic cuff and Hook and Loop TRP closure tab provides a secure fit.

- Two-way form fitting stretch spandex on the back of the hand increasing ventilation, fit and comfort.
- High visibility silver reflective knuckle bar.
- Ventilated finger walls for increased comfort.
- Reinforced synthetic leather thumb, index, middle and ring fingertips.
- Heavy duty elastic cuff with TPR Pull Tab with Hook and Loop closure for secured fit and pulse protection.
- Silicon finger tips for added grip.
- Perforated fourchettes (finger walls).
- Machine washable.

PRODUCT CODE	SIZE
ELG0100M	MEG
ELG0100L	LRG
ELG0100XL	XLG
ELG0100XXL	2XL

OTHER MEC-FLEX GLOVES

			
Mec-Flex Utility Pro	Mec-Flex Utility Gold C5 360	Mec-Flex Oiler Pro C5	Mec-Flex Rigger GT

CERTIFICATIONS & STANDARDS

These Gloves are certified by SAI Global to AS/NZS 2161.3:2005 and EN388



AS/NZS 2161.2 EN420



General Requirements
Risk Category
Sizing
Marking/labelling etc

AS/NZS 2161.3 EN388



Mechanical Hazards - Performance Levels

Test	Level 1	Level 2	Level 3	Level 4	Level 5
A: Abrasion resistance	100	500	2000	8000	-
B: Blade cut resistance	1,2	2,5	5,0	10,0	20,0
C: Tear resistance	10	25	50	75	-
D: Puncture resistance	20	60	100	150	-

Information regarding protection refers to the working surface, i.e the palm of the glove which has been submitted for testing. The overall classification for gloves with two or more non-interconnected layers does not necessarily reflect the performance of the outermost layer. The protection levels indicated are only valid for new gloves.

Abrasion resistance
Blade cut resistance
Tear resistance
Puncture resistance